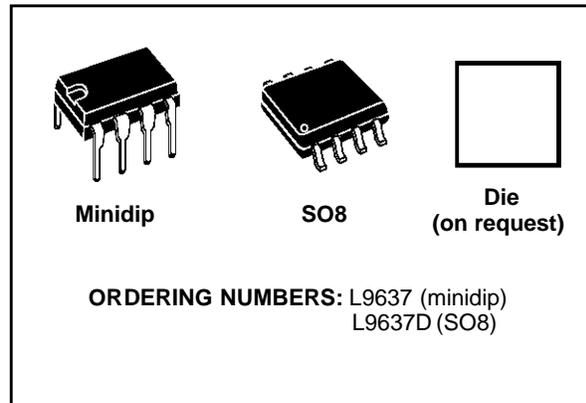


**ISO INTERFACE**

- WIDE OPERATING POWER SUPPLY VOLTAGE RANGE 4.5V VS 45V
- REVERSE SUPPLY (BATTERY) PROTECTED DOWN TO VS -24V
- LOW QUIESCENT CURRENT IN OFF CONDITION  $I_{Q_{TYP}} = 100\mu A$
- TTL COMPATIBLE TX INPUT
- BIDIRECTIONAL K-I/O PIN WITH SUPPLY VOLTAGE DEPENDENT INPUT THRESHOLD
- OVERTEMPERATURE SHUT DOWN FUNCTION SELECTIVE TO K-I/O PIN
- HIGH SIGNAL VOLTAGE RANGE -24V VK +45V
- OUTPUT CURRENT LIMITATION  $I_K = 60MA$
- DEFINED OFF OUTPUT STATUS IN UNDERVOLTAGE OR VS OR GND LACK CONDITION
- CONTROLLED OUTPUT SLOPE FOR LOW EMI
- HIGH INPUT IMPEDANCE DURING VS OR GND LACK
- DEFINED OUTPUT ON STATUS OF LO OR RX DURING INPUT SIGNAL LACK AT LI OR K
- DEFINED K OUTPUT OFF DURING TX INPUT SIGNAL LACK

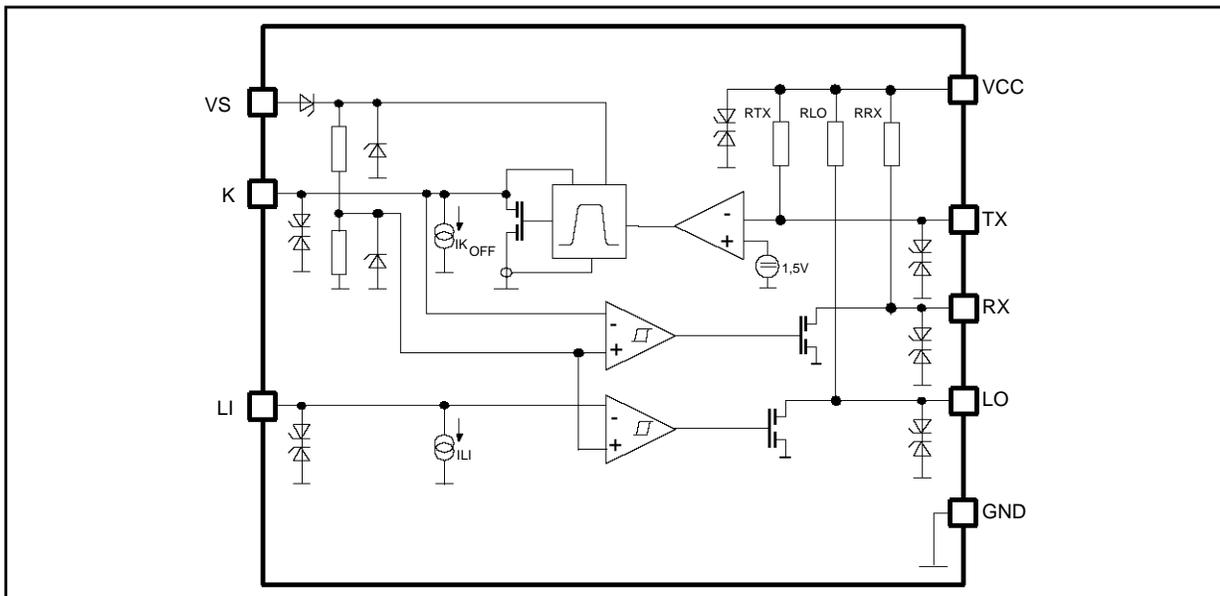


- SEPARATE L COMPARATOR WITH K - I EQUAL FUNCTIONALLITY
- INTEGRATED PULL UP RESISTANCES
- EMV ROBUSTNESS OPTIMIZED
- ESD: ALL PINS ARE GUARANTED TILL 600V

**DESCRIPTION**

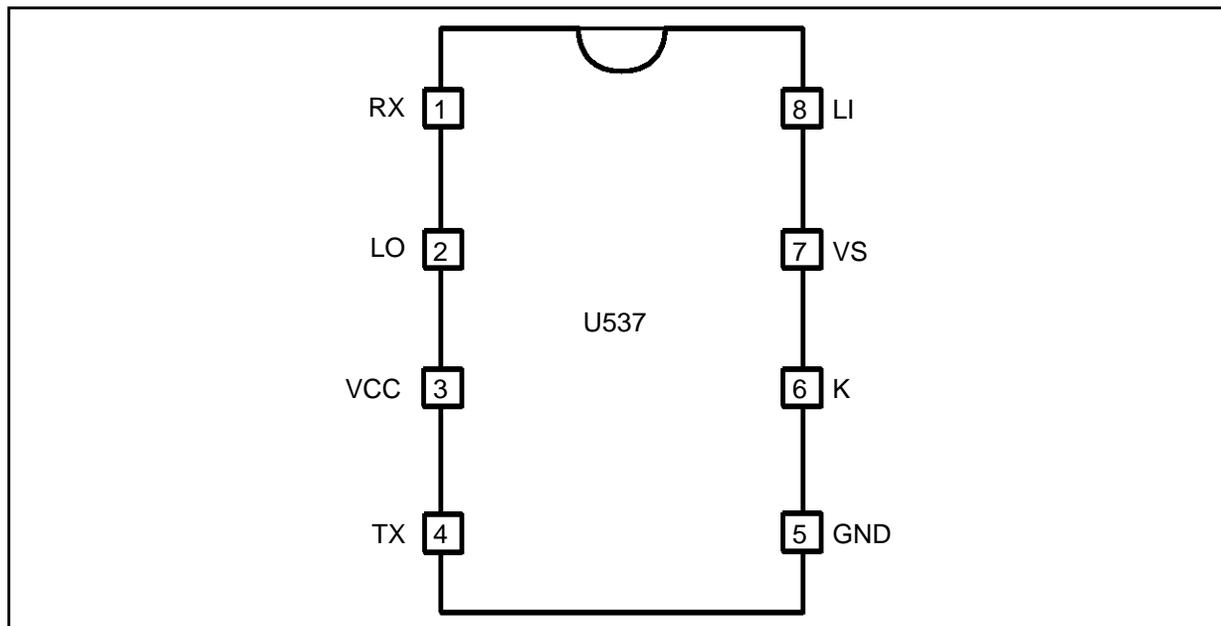
The L9637 is a monolithic integrated circuit containing the whole standard ISO 9141 compatible interface functions.

**BLOCK DIAGRAM**



**ABSOLUTE MAXIMUM RATINGS** (No damage or latch)

Symbol	Parameter	Value	Unit
V <sub>S</sub>	Supply Voltage	-24 to +45	V
V <sub>CC</sub>	Stabilized Voltage	-0.3 to +10	V
V <sub>IN</sub>	Input Voltage @ LI Input Voltage @ TX	-24 to +45 -24 to +10	V V
V <sub>out</sub>	Output Voltage @ K, RX, LO	-24 to +45	V
i <sub>PIN</sub>	Transient pin current t < 2ms to survive interference "Schaffner" pulses in connection with suitable external series resistance	-30 to +30	mA

**PIN CONNECTION** (Top view)**THERMAL DATA**

Symbol	Parameter	Min.	Typ.	Max.	Unit
T <sub>jMonitor</sub>	Temperature K switch off	160	175	190	°C
	Temperature K switch on	140	155	170	°C
R <sub>th j-amb</sub> (*)	Thermal steady state junction to ambient resistance for <b>SO8</b>	130	155	180	°C/W
	Thermal steady state junction to ambient resistance for <b>Minidip</b>	80	100	120	°C/W

(\*) Referring to "Thermal Management in Surface Mount Technology" ST-databook

**PIN DESCRIPTION**

N.	Name	Function
1	RX	Output for K as input
2	LO	Output L comparator
3	VCC	Stabilized voltage supply
4	TX	Input for K as output
5	GND	Common GND
6	K	Bidirectional I/O
7	VS	Supply voltage
8	LI	Input L comparator

**OPERATING RANGE** (The electrical characteristics are valid within the below defined operating range, unless otherwise specified).

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
V <sub>S</sub>	Supply Voltage		4.5	12	36	V
V <sub>CC</sub>	Stabilized Voltage		2	5	10	V
T <sub>j</sub>	Junction temperature		-40		85 *)	°C

\*) Functionally will be guaranteed by design until T<sub>JMon OFF</sub>

## ELECTRICAL CHARACTERISTIC

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
VK <sub>low</sub>	Input Voltage Low state	RX output status LOW 4.5V ≤ V <sub>S</sub> ≤ 20V	-24		0.45V <sub>S</sub>	V
		RX output status LOW 20V ≤ V <sub>S</sub>	-24		8	V
VK <sub>high</sub>	Input Voltage High state	RX output status HIGH 4.5V ≤ V <sub>S</sub> ≤ 20V	0.55V <sub>S</sub>		45	V
		RX output status HIGH 20V ≤ V <sub>S</sub>	12		45	V
VK <sub>hys</sub>	Input Threshold Hysteresis			0.025 V <sub>S</sub>	0.8	V
IK <sub>off</sub>	Input Current	V <sub>TX</sub> ≥ V <sub>TXhigh</sub> 2 < VK ≤ 45V -24V ≤ VK ≤ 2V	1 -5	2	10 25	μA μA
RK <sub>ON</sub>	Output ON Impedance	V <sub>TX</sub> ≤ V <sub>TXlow</sub> @ V <sub>S</sub> > 6.5V @ V <sub>S</sub> ≥ 4.5V		10 45	30 90	Ω Ω
IK <sub>SC</sub>	Short Circuit Current		30	60	100	mA
V <sub>TXlow</sub>	Input voltage LOW state		-24		1	V
V <sub>TXhigh</sub>	Input voltage HIGH state		2		10	V
		@ V <sub>S</sub> > 16V	2.5		10	V
RR <sub>O</sub> RLO <sub>O</sub>	Output ON Impedance	VK ≤ VK <sub>low</sub> ; VLI ≤ VLI <sub>low</sub> @ V <sub>S</sub> > 6.5V @ V <sub>S</sub> ≥ 4.5V		40 180	90 360	Ω Ω
IR <sub>XSC</sub> ILO <sub>SC</sub>	Output Short Circuit Current		9	20	30	mA
VR <sub>XH</sub> VLO <sub>H</sub>	Output Voltage HIGH state	10MΩ ≤ R <sub>LRX</sub> 10MΩ ≤ R <sub>LRX</sub>	V <sub>CC</sub> - 0.25	V <sub>CC</sub> - 0.1	V <sub>CC</sub>	V
RLO RRX	Output pull-up resistance	Output status = (HIGH) -0.15V ≤ VLO ≤ V <sub>CC</sub> + 0.15V -0.15V ≤ VRX ≤ V <sub>CC</sub> + 0.15V	6	10	18	KΩ
RTX	Input pull up resistance	-0.15V ≤ V <sub>TX</sub> ≤ V <sub>CC</sub> + 0.15V	12	20	36	KΩ
VLI <sub>low</sub>	Input voltage LOW state	LO output status LOW 4.5V ≤ V <sub>S</sub> ≤ 20V	-24		0.45V <sub>S</sub>	V
		LO output status LOW 20V ≤ V <sub>S</sub>	-24		8	V
VLI <sub>high</sub>	Input voltage HIGH state	LO output status HIGH 4.5V ≤ V <sub>S</sub> ≤ 20V	0.55V <sub>S</sub>		45	V
		LO output status HIGH 20V ≤ V <sub>S</sub>	12		45	V
VLI <sub>hys</sub>	Input threshold hysteresis			0.025V <sub>S</sub>	0.8	V
ILI	Input current	2V < VLI ≤ 45V	1	2	10	mA
		-24V ≤ VLI ≤ 2V	-5	2	10	μA

ELECTRICAL CHARACTERISTIC (continued)

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
$C_{ki, LO, RX}$	Internal output capacities				20	pF
$f_{LI-LO}$ $f_{K-RX}$ $f_{TX-K}$	Transmission Frequency	$9V < V_S < 16V$ (external loads) $R_{KO} = 510\Omega, C_K \leq 1.3nF$	50	100		kHz
$t_{rLI-LO}$ $t_{rK-RX}$ $t_{rTX-K}$	Rise Time	for the definition of $t_1, t_2$ see fig.1.		2	6	$\mu s$
$t_{fLI-LO}$ $t_{fK-RX}$ $t_{fTX-K}$	Fall Time	$9V < V_S < 16V$ (external loads) $R_{KO} = 510\Omega, C_K \leq 1.3nF$		2	6	$\mu s$
$t_{OFF,LI-LO}$ $t_{OFF,K-RX}$ $t_{OFF,TX-K}$	Switch OFF time	for the definition of $t_{on}, t_{OFF}$ see fig.1.		4	17	$\mu s$
$t_{ON,LI-LO}$ $t_{ON,K-RX}$ $t_{ON,TX-K}$	Switch ON time	$9V < V_S < 16V$ (external loads) $R_{KO} = 510\Omega, C_K \leq 1.3nF$		4	2.3	$\mu s$
$I_{CC}$	Supply Current	$V_{CC} \leq 5.5V, V_{LI}, V_{TX} = 0V$		1.4	2	mA
		$V_{LI} \geq V_{LI_{high}}$ $V_{TX} \geq V_{TX_{high}}$ @ $V_{CC} \leq 5.5V, T_j \leq 85^\circ C$	-5	<1	5	$\mu A$
$I_S$	Supply current	$V_S \leq 16V, V_{LI}, V_{TX} = 0V$		1.2	2	mA
		$V_{LI} \geq V_{LI_{high}}$ $V_{TX} \geq V_{TX_{high}}$ @ $V_S \leq 12V, T_j \leq 85^\circ C$		100	160	$\mu A$

Figure 1.

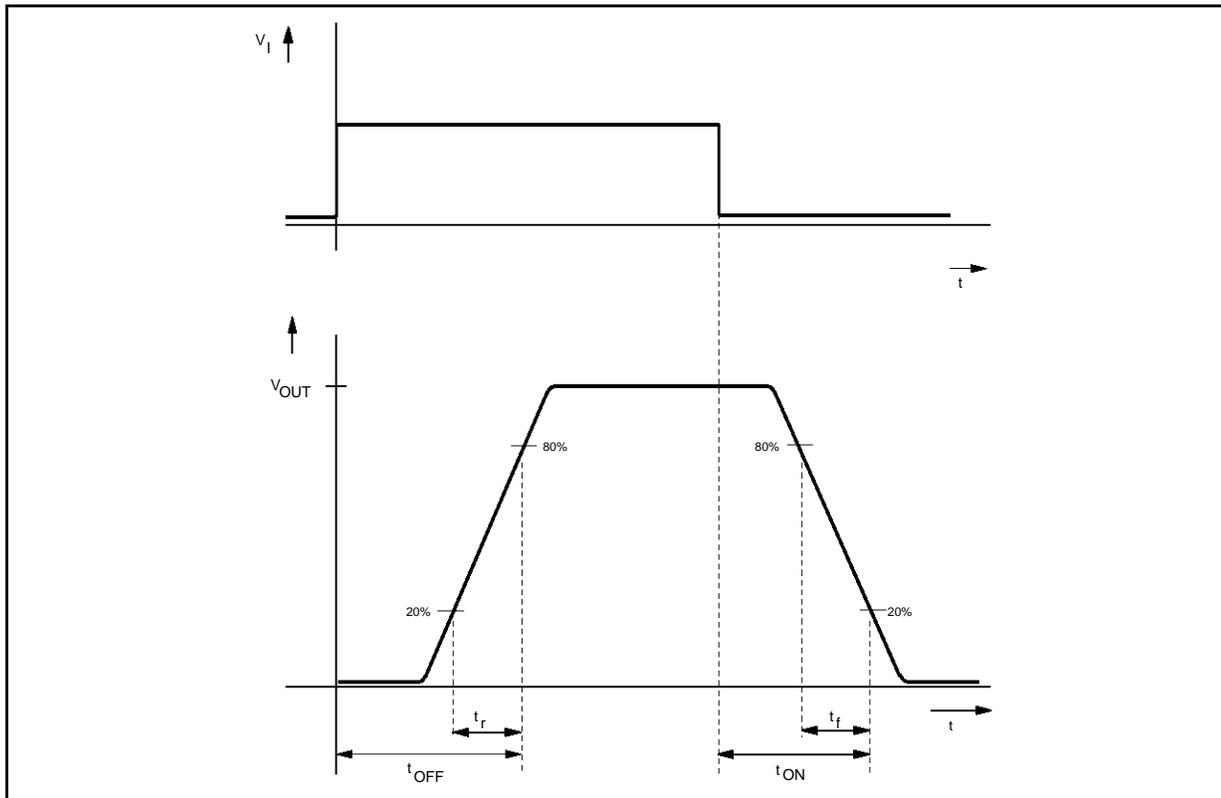
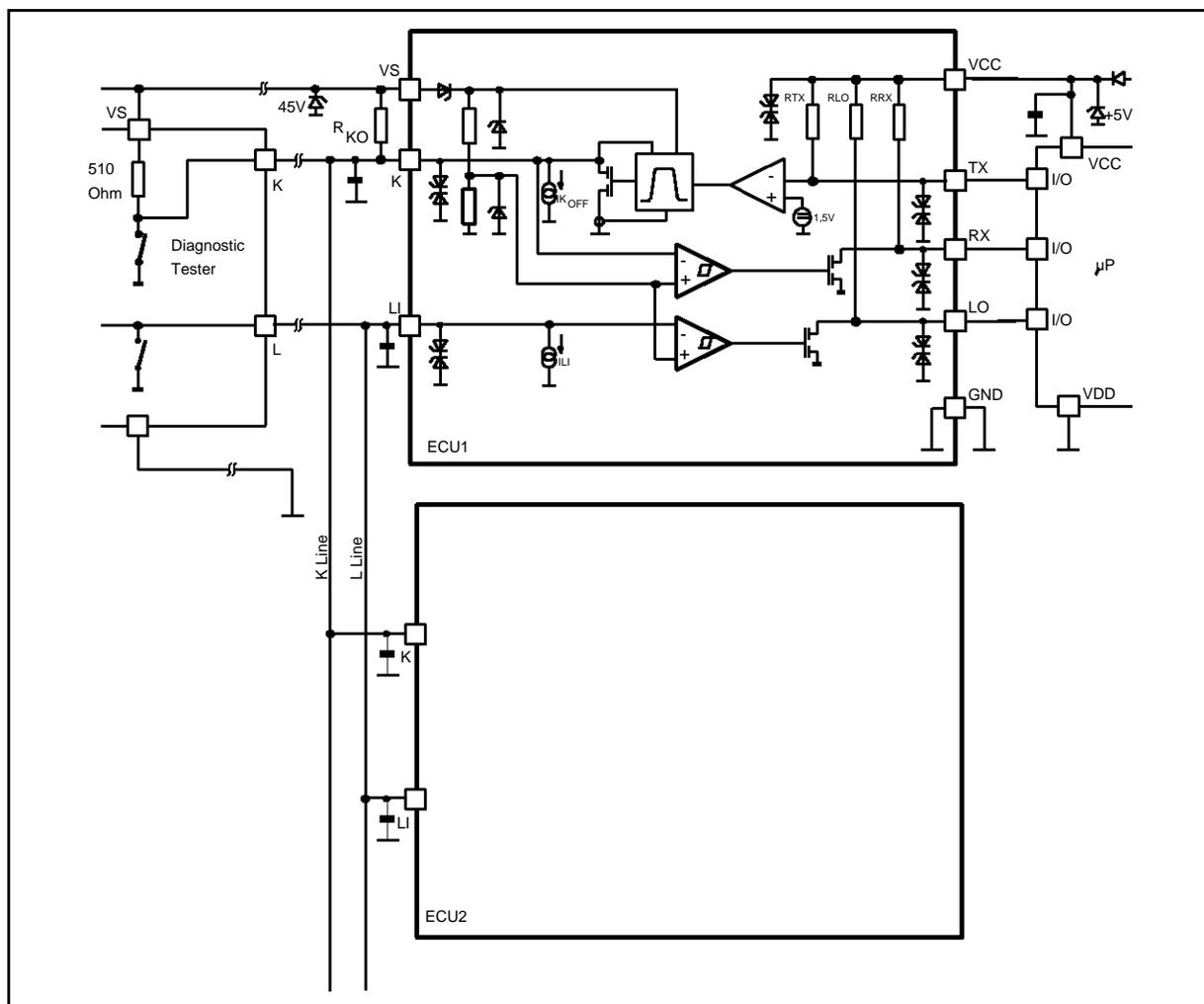


Figure 2: ISO Application Circuit



### FUNCTIONAL DESCRIPTION

The L9637 is a monolithic bus driver designed to provide bidirectional serial communication in automotive diagnostic applications according to the specification "Diagnostic Systems ISO9141".

The device provides a bidirectional link, called K, to the  $V_{Bat}$  related diagnosis bus. It also includes a separate comparator L which is also able to be linked to the  $V_{Bat}$  bus. The input TX and output RX of K are related to  $V_{CC}$  with her integrated pull up resistances. Also the L comparator output LO has a pull up resistance connected to  $V_{CC}$ .

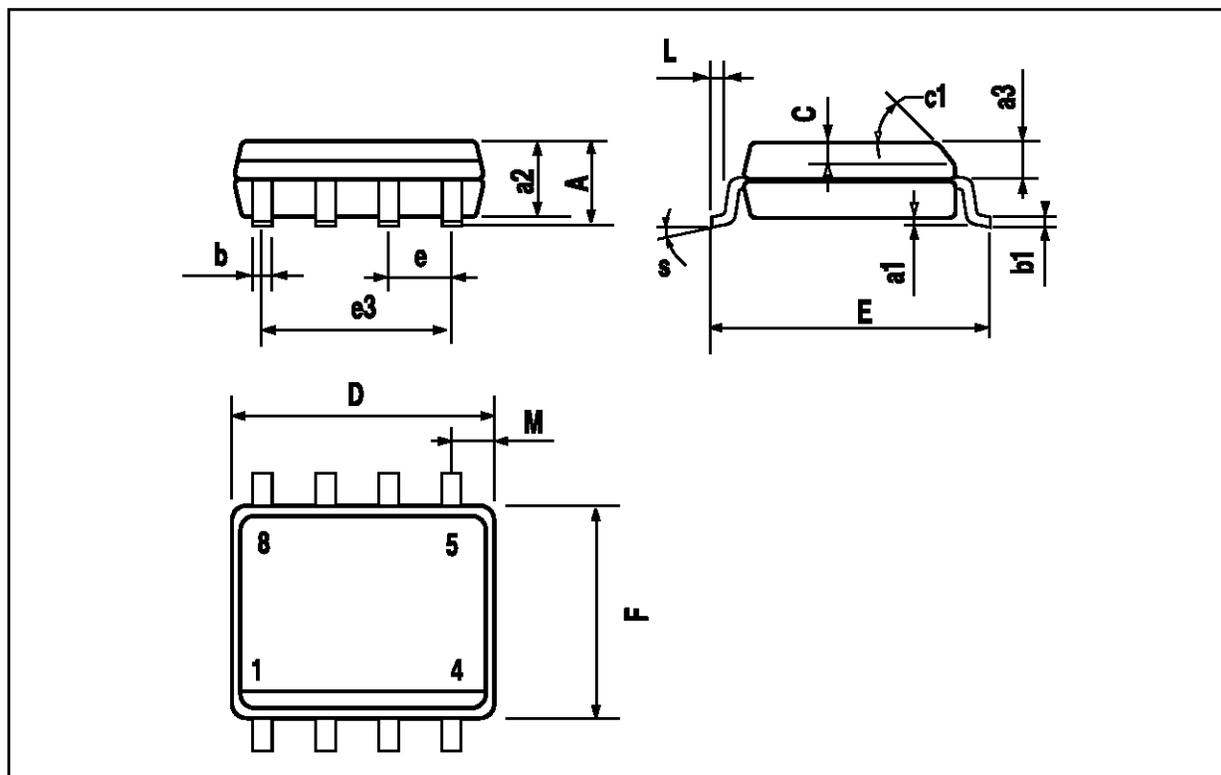
The maximum external pull up resistance at K related to  $V_S$  should not be higher than  $R_{KO} \leq 5K\Omega$  to achieve clear output conditions.

All  $V_{Bat}$  bus defined inputs LI and K have supply voltage dependent thresholds together with sufficient hysteresis to suppress line spikes. These pins are protected against overvoltages, shorts to GND and  $V_S$  and can also be driven beyond  $V_S$

and GND. These features are also given for TX, RX and LI only taking into account the behaviour of the internal pull up resistances. The thermal shut down function switches OFF the K output if the chip temperature increases above the thermal shut down threshold. To achieve no fault for  $V_S$  undervoltage conditions the outputs will be switched OFF and stay at high impedance. The device is also protected against reverse battery condition. During lack of  $V_S$  or GND all pins shows high impedance characteristic. To realize a lack of the  $V_S$  related bus line LI and K the outputs LO and RX shows defined ON status. Suppressing all 4 classes of "Schaffner" signals all pins can be load with short current pulses  $t \leq 2ms$  of max.  $\pm 30mA$ . All these features together with a high possible baud rate  $>100Kbaud$ , controlled output slopes for low EMI, a wide power supply voltage range and a very small quiescent current during OFF condition  $I_q \leq 80\mu A$  make this device high efficient for ISO diagnosis bus systems.

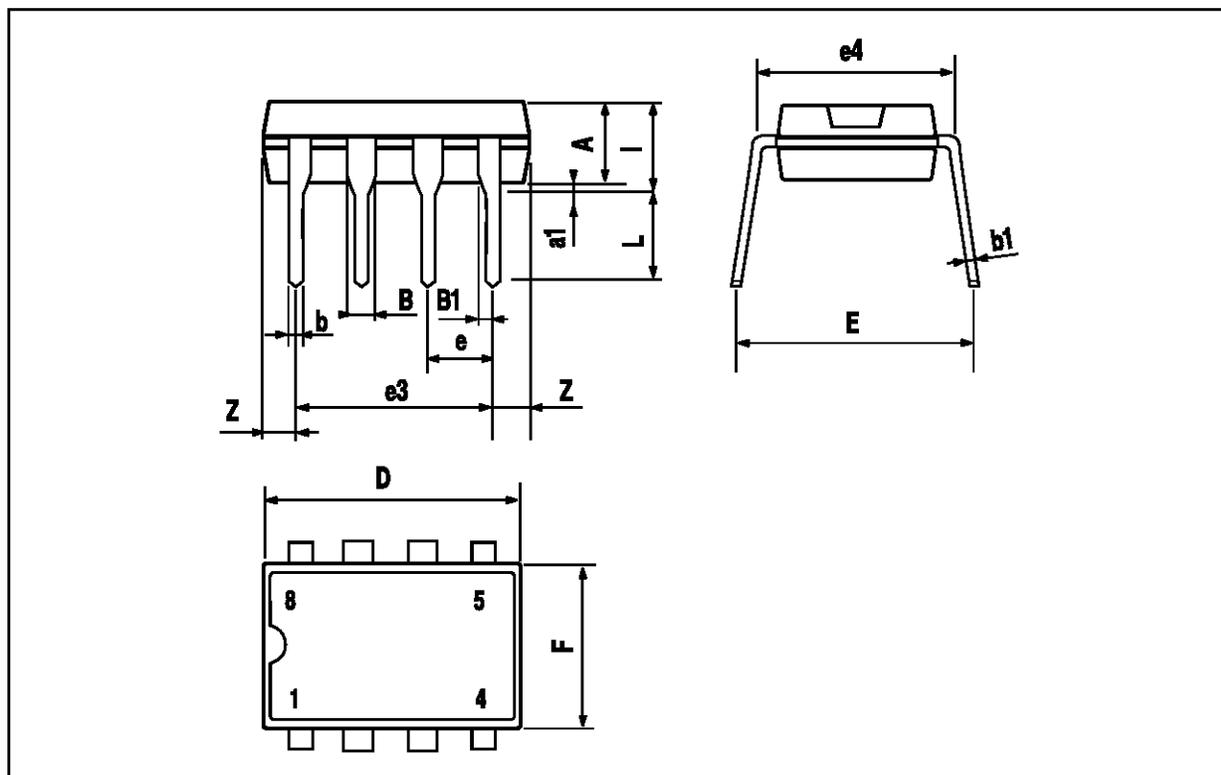
## SO8 PACKAGE MECHANICAL DATA

DIM.	mm			inch		
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
A			1.75			0.069
a1	0.1		0.25	0.004		0.010
a2			1.65			0.065
a3	0.65		0.85	0.026		0.033
b	0.35		0.48	0.014		0.019
b1	0.19		0.25	0.007		0.010
C	0.25		0.5	0.010		0.020
c1	45° (typ.)					
D	4.8		5.0	0.189		0.197
E	5.8		6.2	0.228		0.244
e		1.27			0.050	
e3		3.81			0.150	
F	3.8		4.0	0.15		0.157
L	0.4		1.27	0.016		0.050
M			0.6			0.024
S	8° (max.)					



## MINIDIP PACKAGE MECHANICAL DATA

DIM.	mm			inch		
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
A		3.32			0.131	
a1	0.51			0.020		
B	1.15		1.65	0.045		0.065
b	0.356		0.55	0.014		0.022
b1	0.204		0.304	0.008		0.012
D			10.92			0.430
E	7.95		9.75	0.313		0.384
e		2.54			0.100	
e3		7.62			0.300	
e4		7.62			0.300	
F			6.6			0.260
I			5.08			0.200
L	3.18		3.81	0.125		0.150
Z			1.52			0.060



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